

```
// Import the Serial library for communication with external devices.
import processing.serial.*;

// Declare global variables.
Serial port;
static String val;
int sensorVal0 = 0;
int sensorVal1 = 0;
int sensorVal2 = 0;
int numFireflies = 200;

// Create an array to store instances of the Firefly class.
Firefly[] fireflies = new Firefly[numFireflies];

// Setup function runs once at the beginning.
void setup() {
    // Set the canvas size and frame rate.
    size(1090, 720);
    frameRate(60);

    // Establish a connection to the serial port (adjust "COM5" as needed) at a baud rate of 9600.
    port = new Serial(this, "COM5", 9600);

    // Initialize the array of fireflies.
    for (int i = 0; i < numFireflies; i++) {
        fireflies[i] = new Firefly();
    }
}
```

```

// Draw function runs continuously in a loop.

void draw() {

    // Check if there is data available on the serial port.

    if (port.available() > 0) {

        // Read the data from the serial port until a newline character is encountered.

        val = port.readStringUntil('\n');

        // Print the received data to the console for debugging.

        println("Received data: " + val);


        // Split the received data into three parts based on the "-" delimiter.

        String[] sensorValues = split(val, '-');


        // Ensure that there are three parts in the split data.

        if (sensorValues.length == 3) {

            try {

                // Attempt to convert each part to an integer and store them in sensorVal0, sensorVal1, sensorVal2.

                sensorVal0 = Integer.parseInt(sensorValues[0].trim());

                sensorVal1 = Integer.parseInt(sensorValues[1].trim());

                sensorVal2 = Integer.parseInt(sensorValues[2].trim());


                // Print the converted sensor values to the console for debugging.

                println("Converted sensor values: " + sensorVal0 + ", " + sensorVal1 + ", " + sensorVal2);

            }

            catch (NumberFormatException e) {

                // Handle any exceptions that may occur during the conversion.

                println("Error converting to integer");

            }

        }

        else {

```

```

        // Print a warning if the data does not have the expected format.
        println("Invalid data format");
    }
}

// Set the background color to black.
background(0);

// Iterate through the array of fireflies.
for (int i = 0; i < numFireflies; i++) {
    // Move and display each firefly if it is alive.
    fireflies[i].move();
    fireflies[i].display();
}
}

// Firefly class definition.
class Firefly {
    // Declare instance variables for the firefly's position, movement, and status.
    float x, y;
    float angle;
    float speed;

    // Constructor function called when a new Firefly object is created.
    Firefly() {
        // Call the respawn function to initialize the firefly's properties.
        respawn();
    }
}

```

```
// Respawn function resets the firefly's position and status.
```

```
void respawn() {
```

```
    // Set the firefly's position to a random location within the canvas.
```

```
    x = random(width);
```

```
    y = random(height);
```

```
    // Set the firefly's movement properties to random values.
```

```
    angle = map(sensorVal1, 0, 1023, 0, TWO_PI);;
```

```
    speed = random(1, 3); // speed
```

```
}
```

```
// Move function updates the firefly's position based on its movement properties.
```

```
void move() {
```

```
    float scatteringSpeed = 5; // Adjust this value for scattering effect
```

```
    float slowSpeed = 0.5; // Adjust this value for slow movement effect
```

```
    // Check if any sensor value is outside the desired range
```

```
    if (sensorVal0 > 1000 || sensorVal0 < 80) {
```

```
        // If any sensor value is outside the range, scatter by increasing the speed
```

```
        x += cos(angle) * scatteringSpeed;
```

```
        y += sin(angle) * scatteringSpeed;
```

```
    } else {
```

```
        // If sensor value is within the range, move slowly
```

```
        x += cos(angle) * slowSpeed;
```

```
        y += sin(angle) * slowSpeed;
```

```
    }
```

```
// Check if the firefly is outside the canvas boundaries.
```

```
if (x < 0 || x > width || y < 0 || y > height) {  
    // If so, call the respawn function to reset the firefly's properties.  
    respawn();  
}  
}
```

```
// Display function draws the firefly on the canvas.
```

```
void display() {  
    // Draw a glowing effect around the firefly.  
    for (int i = 3; i > 0; i--) {  
        float glowSize = i * 6;  
        int glowAlpha = 20 - i * 5;  
        fill(255, 255, 0, glowAlpha);  
        ellipse(x, y, 20 + glowSize, 20 + glowSize);  
    }  
}
```

```
// Draw the central part of the firefly.  
noStroke();  
fill(255, 255, 0);  
ellipse(x, y, 2, 2);  
}  
}
```