Body-schemata (Mark Johnson)

- Container
- Blockage
- Enablement
- Path
- Cycle
- Part-whole
- Full-empty
- Iteration
- Surface
- Balance
- Counterforce
- Attraction
- Link
- Near-far
- Merging
- Matching
- Contact
- Object
- Compulsion
- Restraint removal
- Mass-count
- Center-periphery
- Scale
- Splitting
- Superimposition
- Process
- Collection

Schemas discussed by Johnson[edit]

Spatial motion group

- Containment
- Path
- Source-Path-Goal
- Blockage
- Center-Periphery
- Cycle
- Cyclic Climax

Force Group

- Compulsion
- Counterforce
- Diversion
- Removal of Restraint
- Enablement
- Attraction

- Link
- Scale

Balance Group

- Axis Balance
- Point Balance
- Twin-Pan Balance
- Equilibrium

Other:

- Contact
- Surface
- Full-Empty
- Merging
- Matching
- Near-Far
- Mass-Count
- Iteration
- Object
- Splitting
- Part-Whole
- Superimposition
- Process
- Collection

Additional schemas discussed by Lakoff

- Transformational group
- Linear path from moving object (one-dimensional trajector)
- Path to endpoint (endpoint focus)
- Path to object mass (path covering)
- Multiplex to mass (possibly the same as Johnson's undefined Mass-Count)
- Reflexive (both part-whole and temporally different reflexives)
- Rotation
- Spatial group
- Above
- Across
- Covering
- Contact
- Vertical Orientation
- Length (extended trajector)